for the electric motor 66 with electric motor gear box and shaft assembly 62, 64, 65, and 66.

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Consequently, the motor ultimately turns the shaft 60 and through the three flexible links described, transfers energy to the pulley 50 thus turning the treadmill conveyor. All of the above is accomplished utilizing the same pivot points as created by the two rigid structure members combined. The motor 66 and the 30 are controlled by electrical signals at 70 and 68 respectively. The signal 70 controls the speed of the motor as does the signal 68. Both signals at 68 and 70 are generated from the control microprocessor as shown in Figure 7.

It will also be seen that the water 3 penetrates the wall section between interior wall 5 and exterior end wall 72 and that the chain and sprocket assembly 18, 22, and 17 is inside the unit in the water and consequently water tight seals at 22 and 17 as well as at 40 are necessary. However the invention is designed in this manner so as to provide for apparatus that will most easily allow water tight seals through the enclosure. Moreover, the support structure (rigid members 32 and 34) allow for least contamination of the water Other devices provide for hydraulic by the mechanical system. mechanisms inside the tank, an undesirable structure inasmuch as hydraulics are unclean, allow for leaks of the fluid and in the therapeutic environment are normally entirely undesirable. Consequently the support structure and the lifting structure, are not only unique in themselves but provide for a far more hygienic system.

The side view in Figure 2 shows the fixed point at which the rigid member 32 is fixed. Also the inside wall 78 is shown though as indicated earlier, the chain and sprocket mechanism 80 is normally